



ALBION PARK, QLD  
 Race 7 - ROSEWOOD VETERINARY SERVICE - 520M  
 24/06/2024 - 20:56:37 PM

| RUG | NAME            | BOX | TOP SPEED | 50M                            | 100M                           | 150M                           | 200M                            | 250M                            | 300M                            | 350M                            | 400M                            | 450M                            | 500M                            | 217M HOME                   | FINISH TIME |
|-----|-----------------|-----|-----------|--------------------------------|--------------------------------|--------------------------------|---------------------------------|---------------------------------|---------------------------------|---------------------------------|---------------------------------|---------------------------------|---------------------------------|-----------------------------|-------------|
|     | Trapper Tears   | 2   | 70.7km/h  | 3.75 [2]<br>52.1km/h<br>(0.6M) | 6.37 [2]<br>68.6km/h<br>(0.3M) | 8.95 [1]<br>69.7km/h<br>(0.3M) | 11.61 [1]<br>67.8km/h<br>(0.6M) | 14.35 [1]<br>65.7km/h<br>(1.7M) | 17.05 [1]<br>66.8km/h<br>(2.2M) | 19.82 [1]<br>65.0km/h<br>(1.8M) | 22.72 [1]<br>62.0km/h<br>(1.7M) | 25.69 [1]<br>60.5km/h<br>(0.7M) | 28.70 [1]<br>59.9km/h<br>(0.7M) | 12.67<br>61.7km/h<br>(1.2M) | 29.88 [1]   |
|     | Cleopatra Hayze | 8   | 68.6km/h  | 3.75 [3]<br>51.7km/h<br>(3.4M) | 6.44 [3]<br>67.0km/h<br>(2.1M) | 9.08 [3]<br>68.1km/h<br>(1.2M) | 11.78 [3]<br>66.6km/h<br>(1.3M) | 14.58 [2]<br>64.3km/h<br>(2.0M) | 17.33 [2]<br>65.6km/h<br>(2.6M) | 20.18 [2]<br>63.1km/h<br>(1.7M) | 23.16 [2]<br>60.6km/h<br>(1.7M) | 26.14 [2]<br>60.3km/h<br>(0.9M) | 29.13 [2]<br>60.1km/h<br>(1.0M) | 12.83<br>61.0km/h<br>(1.3M) | 30.32 [2]   |
|     | Blaze Duck      | 4   | 68.4km/h  | 3.78 [4]<br>51.8km/h<br>(2.2M) | 6.47 [4]<br>66.7km/h<br>(1.4M) | 9.13 [4]<br>67.5km/h<br>(0.7M) | 11.88 [4]<br>65.5km/h<br>(0.8M) | 14.67 [4]<br>64.4km/h<br>(1.6M) | 17.39 [3]<br>66.2km/h<br>(2.2M) | 20.30 [3]<br>62.0km/h<br>(2.1M) | 23.33 [3]<br>59.6km/h<br>(2.1M) | 26.34 [3]<br>59.7km/h<br>(0.8M) | 29.34 [3]<br>59.9km/h<br>(0.7M) | 12.96<br>60.4km/h<br>(1.3M) | 30.52 [3]   |
|     | Speedy Paws     | 1   | 69.3km/h  | 3.86 [7]<br>51.0km/h<br>(0.3M) | 6.54 [7]<br>67.0km/h<br>(0.1M) | 9.19 [6]<br>68.0km/h<br>(0.2M) | 11.93 [6]<br>65.7km/h<br>(0.5M) | 14.75 [6]<br>63.9km/h<br>(1.2M) | 17.50 [6]<br>65.3km/h<br>(1.5M) | 20.36 [4]<br>63.1km/h<br>(1.5M) | 23.38 [4]<br>59.7km/h<br>(1.3M) | 26.41 [4]<br>59.4km/h<br>(0.6M) | 29.43 [4]<br>59.5km/h<br>(0.2M) | 12.95<br>60.4km/h<br>(0.8M) | 30.62 [4]   |
|     | Cha Cha Zac     | 5   | 68.3km/h  | 3.80 [5]<br>51.3km/h<br>(2.7M) | 6.51 [6]<br>66.3km/h<br>(1.8M) | 9.19 [7]<br>67.3km/h<br>(1.0M) | 11.96 [7]<br>65.0km/h<br>(1.3M) | 14.78 [7]<br>63.9km/h<br>(2.0M) | 17.51 [7]<br>65.8km/h<br>(3.0M) | 20.38 [5]<br>62.7km/h<br>(2.1M) | 23.42 [5]<br>59.2km/h<br>(1.7M) | 26.50 [5]<br>58.6km/h<br>(1.0M) | 29.54 [5]<br>59.0km/h<br>(1.3M) | 13.07<br>59.9km/h<br>(1.5M) | 30.75 [5]   |
|     | Glen's Wish     | 6   | 69.0km/h  | 3.82 [6]<br>51.4km/h<br>(3.0M) | 6.50 [5]<br>67.2km/h<br>(2.3M) | 9.14 [5]<br>68.2km/h<br>(1.5M) | 11.88 [5]<br>65.5km/h<br>(1.8M) | 14.71 [5]<br>63.9km/h<br>(2.7M) | 17.47 [5]<br>65.1km/h<br>(4.1M) | 20.40 [7]<br>61.5km/h<br>(3.2M) | 23.54 [6]<br>57.5km/h<br>(2.9M) | 26.60 [6]<br>58.7km/h<br>(0.9M) | 29.67 [6]<br>58.7km/h<br>(0.6M) | 13.24<br>59.1km/h<br>(1.8M) | 30.88 [6]   |
|     | Uno Cha Cha     | 3   | 70.1km/h  | 3.69 [1]<br>52.5km/h<br>(1.9M) | 6.34 [1]<br>67.9km/h<br>(1.4M) | 8.96 [2]<br>68.6km/h<br>(0.9M) | 11.74 [2]<br>64.9km/h<br>(1.6M) | 14.61 [3]<br>62.7km/h<br>(2.6M) | 17.41 [4]<br>64.4km/h<br>(3.7M) | 20.39 [6]<br>60.4km/h<br>(3.0M) | 23.59 [7]<br>56.3km/h<br>(2.4M) | 26.72 [7]<br>57.5km/h<br>(0.7M) | 29.84 [7]<br>57.8km/h<br>(1.5M) | 13.48<br>58.0km/h<br>(1.9M) | 31.06 [7]   |

Data based on IsoLynx Localised Positioning System.

Legend:

[ ] - Rank at each section

( ) - Avg. meters to rail for section

-- - No data available at section

